The PST-360 through hole / hollow-shaft position sensors combine three critical design features: 1) through hole where the shaft passes through the sensor, 2) high accuracy absolute position feedback over up to 360 degrees, and 3) a true non-contacting sensing element. Piher’s design does not rely on gears or other rotating parts.

This innovative and unique patented design features the following advantages:
- Complements the attributes of the target application.
- Mechanical integrity that matches customer’s application by design.
- Unique shaft mounted design that mounts at the pivot point of the application.
- No levers, connecting rods or mechanical interfaces needed.
- Adapts to shaft’s eccentricity, mounting tolerances and mechanical wear over the life of the application.

### Mechanical specifications

- **Rotational life (depends on application and mounting)**: up to 50,000,000 cycles.
- **Operating temperature**: -40°C to +125°C.

### Electrical specifications

- **Linearity**: ±1% absolute (0.5% upon request).
- **Angular range**: Programmable from 15 to 360 degrees.
- **Output**: Analog (Ratiometric), PWM. Serial protocol (SPI) and CAN SAE J1939 upon request.
- **Switch output**: Upon request. Programmable.
- **Angular Resolution (depends on electrical angle and rotational speed)**: Analog & PWM: up to 12 bits. Serial Protocol (SPI): up to 14 bits.
- **Supply voltage**: Up to 25V.
- **Supply current**: Typ 8.5mA for single version. Typ 17mA for redundant version.

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1. Others check availability. Ferromagnetic materials close to the sensor (i.e. shaft, mounting surface) may affect the sensor’s linearity. Please contact Piher for advise.
2. CAN protocol: check for available versions before ordering.
# Magnetic rotary hollow-shaft position sensor/control

## Contactless sensor

### PST-360

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**How to order** *(example: PST360-1A-C0018-ERA190-05K)*

### Simple output

<table>
<thead>
<tr>
<th>PST360G2</th>
<th>Series</th>
<th>Rotor</th>
<th>Type</th>
<th>Output</th>
<th>Output function</th>
<th>Electrical rotation angle</th>
<th>Voltage supply</th>
<th>Temp. range</th>
<th>PWM Frequency (Hz)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>[empty] = 14mm B = 17mm</td>
<td>1=simple</td>
<td></td>
<td>C0000</td>
<td>ERA015</td>
<td>05 RE</td>
<td>K=40 to +125°C</td>
<td>F100</td>
</tr>
</tbody>
</table>

---

### Redundant output

<table>
<thead>
<tr>
<th>PST360G2</th>
<th>Series</th>
<th>Rotor</th>
<th>Type</th>
<th>Output</th>
<th>Output function</th>
<th>Electrical rotation angle</th>
<th>Voltage supply</th>
<th>Temp. range</th>
<th>PWM Frequency (Hz)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>[empty] = 14mm B = 17mm</td>
<td>2= redundant</td>
<td></td>
<td>C0002</td>
<td>ERA015</td>
<td>05 RE</td>
<td>K=40 to +125°C</td>
<td>F100</td>
</tr>
</tbody>
</table>

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### Full redundant output

<table>
<thead>
<tr>
<th>PST360G2</th>
<th>Series</th>
<th>Rotor</th>
<th>Type</th>
<th>Output</th>
<th>Output function</th>
<th>Electrical rotation angle</th>
<th>Voltage supply</th>
<th>Temp. range</th>
<th>PWM Frequency (Hz)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>[empty] = 14mm B = 17mm</td>
<td>3=full redundant</td>
<td></td>
<td>C0002</td>
<td>ERA015</td>
<td>05 RE</td>
<td>K=40 to +125°C</td>
<td>F100</td>
</tr>
</tbody>
</table>

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**Notes**

1. Other rotors: check availability.
2. The analog output is a ratiometric output, proportional to:
   - For supply voltage 5V: to input supply voltage.
   - For supply voltage RE: to 5V.
3. 05: 5V ±10%
   RE: 7V - 25V
4. Other output functions available check availability. In the How To Order reference, enter **CXXXX** meanwhile the new output function reference is not defined.
   E.g.: PST360-1A-CXXXX-ERA190-05K
5. Leave empty if no applicable. Default frequency is 200 Hz
Magnetic rotary hollow-shaft position sensor/control

Contactless sensor
PST-360

Dimensions
Hollow shaft diameter 14mm.

Rotor is shown at zero position. Sensor is delivered at random position.

Recommended shaft dimensions.

Rotor - Detail A
Magnetic rotary hollow-shaft position sensor/control

Contactless sensor
PST-360

Dimensions
Hollow shaft diameter 17mm.

Mounting instructions
1.- Place the component on a flat surface.
2.- Fit the shaft of the application (see recommended shaft dimensions) through the sensor’s rotor avoiding any mechanical play/wobble.
3.- Fasten the two M5 screws (M5 washers are recommended).
Magnetic rotary hollow-shaft position sensor/control

Contactless sensor

PST-360

Connections scheme

Simple analog output connection wiring scheme. Other versions available upon request.

Brown = Power supply.
Blue = Ground.
Black = Signal output.
White = Not used.
Grey = Not used.

Fly leads with Wire: 0.35mm². TXL SAE J1128.
Check availability for the connector options.

Output examples

Disclaimer

Ferromagnetic parts close to the sensor, including the shaft, may modify the performance of the sensor. Therefore, this has to be communicated to Piher for prior analysis.

No external magnetic perturbations are considered on the application where the sensor is mounted. If so, amplitude and direction of flux density generator type and characteristics (magnet, cable, motor...) must be notified to Piher.

The product information in this catalogue is for reference purposes. Please consult for the most up to date and accurate design information.

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